Introduction to General Stokes Theorem

物理系26級林承諺

Introduction of Generalized Stokes theorem

The generalized Stokes theorem is a fundamental idea in math that links the integral of a special function, called a differential form, over a manifold to the integral over its boundary. It states,

$$\int_{\Omega} d\omega = \int_{\partial \Omega} \omega$$

- Ω is an oriented n-dimensional manifold with boundary $\partial \Omega$,
- ω is a smooth (*n*-1)-form
- $d\omega$ is the exterior derivative of ω , resulting in an n-form

This rule generalizes simpler ideas like the fundamental theorem of calculus, Green's theorem, Divergence theorem, and the standard Stokes' theorem.

A brief introduction of p-form

In \mathbb{R}^n , a p-form can be expressed as: $\omega = \omega_{\mu_1 \cdots \mu_p} dx^{\mu_1} \otimes dx^{\mu_2} \otimes \cdots \otimes dx^{\mu_p}$ $= \frac{1}{p!} \omega_{\mu_1 \dots \mu_p} dx^{\mu_1} \wedge dx^{\mu_2} \wedge \cdots \wedge dx^{\mu_p}$ (where \wedge is the wedge product)

Some characteristics of wedge product (A)

- Antisymmetry : $u \wedge v = -v \wedge u$
- Associativity : $(u \land v) \land w = u \land (v \land w)$
- Vanishes for Duplicates : $u \wedge u = 0$
- Relation to area and volume:

```
ex. dx \wedge dy \rightarrow dS
dx \wedge dy \wedge dz \rightarrow dV
dx^0 \wedge dx^1 \wedge \dots \wedge dx^{n-1} \rightarrow general volume
```

Exterior derivative (can only act on p-form)

)

$$d: \omega \to d\omega$$

$$(\omega \text{ is } a p - f \text{ orm, } d\omega \text{ is } a (p+1) f \text{ orm})$$

$$\omega = \frac{1}{p!} \omega_{\mu_1 \dots \mu_p} dx^{\mu_1} \wedge dx^{\mu_2} \wedge \dots \wedge dx^{\mu_p}$$

$$d\omega \stackrel{\text{def}}{=} \frac{1}{p!} (\frac{\partial}{\partial x^{\nu}} \omega_{\mu_1 \dots \mu_p}) dx^{\nu} \wedge (dx^{\mu_1} \wedge dx^{\mu_2} \wedge \dots \wedge dx^{\mu_p})$$

Applications in physics

In Classical Electromagnetism (n-dimensional Cartesian coordinate): ex. Gauss's law

The Integral form:
$$\int_{S} \boldsymbol{E} \cdot d\boldsymbol{A} = \frac{Q_{enc}}{\varepsilon_0} = \int_{V} \frac{\rho}{\varepsilon_0} dV$$

By using divergence theorem, $\int_{V} \boldsymbol{\nabla} \cdot \boldsymbol{E} \, dV = \int_{V} \frac{\rho}{\varepsilon_0} dV$
Which gives the Differential form: $\boldsymbol{\nabla} \cdot \boldsymbol{E} = \frac{\rho}{\varepsilon_0}$

Applications in physics

In Relativistic Electromagnetism(four-dimensional spacetime):

- In four-dimensional spacetime, the electromagnetic field is described by a 2-form F.
- The homogeneous Maxwell equations are dF = 0 Hodge star operator
- The inhomogeneous equations involve the current, written as $d \star F = J$

Consider a four-dimensional spacetime region M with boundary ∂M :

 $\int_M d\star F = \int_M J$

Apply general stokes theorem:

 $\int_{M} J = \int_{\partial M} \star F$

Here, $\int_M J$ represents the total charge passing through the four-dimensional region M, which can be interpreted as the integral of the current density over spacetime. The right-hand side, $\int_{\partial M} *F$, is the integral of the dual field form over the boundary, which, in physical terms, relates to the electric flux through the boundary surfaces.